path to goal: the sequence of moves taken to reach the goal

cost of path: the number of moves taken to reach the goal

nodes expanded: the number of nodes that have been expanded

search depth: the depth within the search tree when the goal node is found

max search depth: the maximum depth of the search tree in the lifetime of the algorithm

running time: the total running time of the search instance, reported in seconds

max ram usage: the maximum RAM usage in the lifetime of the process as measured by the ru maxrss attribute

in the resource module, reported in megabytes

Example

Expand method confused